



```

class Book:
    def __init__(self, name, colour, origin, height, orientation):
        if name == None:
            self.name = random.choice(stri
        else:
            self.name = name
        self.colour = colour
        self.origin = origin
        self.width = width
        self.height = height
        self.depth = depth
        self.orientation =
        self.convertOrientation(orientatio
        self.box = self.getBox()

    def getBox(self):
        a = self.origin
        b = a.translated(self.width * self
            self.width * self.
            self.width * self.
        d = a.translated(self.depth * -sel
            self.depth * self.
            self.depth * self.
        c = b.translated(self.depth * -sel

class Shelf:
    def __init__(self, books):
        self.colour = pygame.Color(200, 200
        self.width = 0
        self.highestBook = 0
        self.height = 200
        self.depth = 200
        self.orientation = books[0].orient
        self.walls = []
        bookDeq = deque()
        for b in books:
            b.orientation = self.orientati
            r = random.randint(0,1)
            if r == 0:
                bookDeq.appendleft(b)
            else:
                bookDeq.append(b)
        self.width += b.width
        if b.height > self.highestBook:
            self.highestBook = b.height
        bookDeq[0].moveTo(Point(0,0,0))
        for i in range(1, len(bookDeq)):
            bookDeq[i].moveTo(copy.deepcopy
                ], box.pB))
        self.books = bookDeq

class ShelvingColumn:
    def __init__(self, hierarchy, origin, i
        shelfLevels):
        self.origin = origin
        self.dir = dir
        self.width = 0
        self.height = 0
        self.depth = 0
        self.box = None
        self.orientation =
        self.convertOrientation(orientatio
        self.shelves = []
        self.hierarchy = hierarchy
        self.colour = pygame.Color(200, 200
        self.walls = None
        self.maxLevels = shelfLevels
        self.bannedDirs = []

    def convertOrientation(self, d):
        l = math.sqrt(d[0]**2 + d[1]**2)
        return [d[0]/l, d[1]/l, 0]

    def getBox(self):
        if self.height == 0 and self.depth
            self.width ==0:

class Walkway:
    def __init__(self, col, walkWidth, hei
        self.walkWidth = walkWidth
        self.pWalkway = pWalkway
        self.height = height
        self.col = col
        self.orientation = col.orientation
        self.v = v
        self.pA = col.box.pA.translated(0,
        self.pB = col.box.pB.translated(0,
        self.pC = col.box.pC.translated(se
            col.orientation[1],
                self.walkWidth
                col.orientatio
                self.walkWidth
                col.orientatio
                self.walkWidth
                col.orientatio
        self.pD = col.box.pD.translated(se
            col.orientation[1],
                self.walkWidth
                col.orientatio
                self.walkWidth
                col.orientatio
        self.box = Box(pygame.Color(0, 0,
        self.pB, self.pC, self.pD, 100)
        self.pillar = []

class Pillars:
    def __init__(self, collections):
        self.collections = collections
        self.walkways = []
        self.pillars = self.getPillars()
        self.floorHeights = self.getFloorH
        self.envelopes = self.getEnvelopes

    def extendPillars(self):
        pillars = []
        for f in range(len(self.floorHeigh
            lengthenPillars = []
            for p in self.pillars[f]:
                p.height += 100
                if not
                    (self.walkwayCollision(sel
                    p) or
                    self.envelopeCollision(sel
                    p)):
                        lengthenPillars.append
            for p in pillars:
                if not
                    (self.walkwayCollision(sel
                    p) or
                    self.envelopeCollision(sel

class Stairs:
    def __init__(self, clusterCreator, wid
        self.clusterCreator = clusterCreat
        self.width = width
        self.depth = depth
        self.height = height
        self.clusters = self.clusterCreato
        self.floors = self.clusterCreato
        self.stairs = []

    def makeStairs(self):
        for n in range(self.floors):
            cluster = self.clusters[n]
            staircase = []
            floorheight = cluster.floorHei
            col = cluster.shelfColumns[-1]
            col.width = self.width
            col.getBox()
            walkway = Step(col.box.colour,
            col.box.pB.translated(0,0,-100
                self.depth, 100, self.
                col.orientation)
            staircase.append(walkway)
            while ((len(staircase)-1) * se
                floorheight - self.height):

class WallPanels:
    def __init__(self, clusterCreator, wid
        maxSteps):
        self.clusterCreator = clusterCreat
        self.width = width
        self.depth = depth
        self.clusters = self.clusterCreato
        self.floors = self.clusterCreato
        self.panels = []
        self.maxSteps = maxSteps
        self.oneFloorNr = 0

    def initiatePanels(self):
        for n in range(self.floors):
            envelope = self.clusterCreator
            height = self.clusters[n].flo
            z = self.clusters[n].origin.z
            lines = envelope.getLines()
            oneFloorNr = 0
            for x in lines:
                l = Line(None, Point(x[0][
                    Point(x[1][0], x[1][1], 0)
                row = []
                oX = l.pointB.x - l.pointA
                oY = l.pointB.y - l.pointA

class FloorBoard:
    def __init__(self, colour, origin, widt
        orientation, floor):
        self.colour = colour
        self.origin = origin
        self.width = width
        self.height = height
        self.depth = depth
        self.orientation =
        self.convertOrientation(orientation
        self.box = self.getBox()
        self.floor = floor

    def getBox(self):
        a = self.origin
        b = a.translated(self.width * self.
            self.width * self.o
            self.width * self.o
        d = a.translated(self.depth * -self
            self.depth * self.o
            self.depth * self.o
        c = b.translated(self.depth * -self
            self.depth * self.o
            self.depth * self.o

class ClusterCreator:
    def __init__(self, n, envelopes, origi
        size, i, shelfLevels):
        self.n = n
        self.i = i
        self.envelopes = envelopes
        self.clusters = []
        self.size = size
        self.otherClusters = []
        self.origin = origin
        self.orientation = orientation
        #self.floorHeight = floorHeight
        self.shelfLevels = shelfLevels
        self.walkWidth = 1200
        self.wallPanels = None

    def create(self):
        prevCollection = None
        for i in range(self.n):
            books = BookCollection(2**self
            shelves = []
            start = self.origin
            startOrientation = self.orient
            for b in range(2**(self.size-5
                set = books.books[b*32:b*33

```